Computing c- and a-functions from Entanglement

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Work with D. Katsinis, G. Pastras, N. Tetradis arXiv:2509.03259 [hep-th]

Quantum Days in Crete 2025

Motivation: RG irreversibility via entanglement

- Quantum field theories flow under the BG from the UV to IR.
- The number of effective degrees of freedom decreases during the flow.
- Irreversibility of RG:
 - (1+1)D: c-function (Zamolodchikov 1986).
 - (2+1)D: *F*-function (Casini-Huerta 2012).
 - (3+1)D: *a*-function (Cardy 1988, Komargodski-Schwimmer 2011).
- These functions are monotonic along the RG flow.
- The entanglement entropy (EE) provides a natural probe of d.o.f.
- Can we compute c and a-functions directly from the entanglement entropy in specific QFTs?

Motivation 2 / 20

What is entanglement entropy?

- Consider a quantum mechanical system with many degrees of freedom.
- Assume it is in the ground state $|\Psi\rangle$ (pure state).
- The density matrix of the total system is $\rho_{\text{tot}} = |\Psi\rangle\langle\Psi|$.
- The von Neumann entropy $S_{tot} = -\text{tr}\rho_{tot}\log\rho_{tot}$ vanishes.
- Now divide the total system into subsystems A and B and assume that B is inaccessible to A.
- Trace out the part B of the Hilbert space in order to obtain the reduced density matrix of A: $\rho_A = \operatorname{tr}_B \rho_{\text{tot}}$.
- The entropy $S(A) = -\text{tr}_A \rho_A \log \rho_A$ is a measure of the entanglement between A and B.

Motivation 3/20

In quantum field theory:

- Define an entangling surface (e.g. a sphere of radius R).
- Divide space into two subsystems A and B.
- S(A) measures quantum correlations across the boundary ∂A .
- S(A) is dominated by short-distance (UV) modes near ∂A .

Generic features:

- Area law: $S(A) \sim \text{Area}(\partial A)/\epsilon^{d-1} + \dots$, with cutoff ϵ .
- Divergent terms ⇒ need subtractions or derivatives to extract universal, physical information.
- Universal subleading terms encode the effective degrees of freedom of the QFT.

Motivation 4 / 20

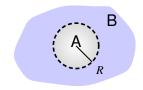
Entanglement entropy as a probe of d.o.f. - flat space

Casini-Huerta, Phys.Lett. B600 (2004) 142-150

Casini-Teste-Torroba, Phys. Rev. Lett. 118, 261602 (2017)

Setup: Consider a QFT in its vacuum state and a spherical entangling surface of radius *R*.

- S(R) is the EE between A and B.



From first principles:

- Poincaré invariance
- Strong subadditivity (SSA)
- Markov property of the vacuum

it has been argued that suitable combinations of derivatives of $\Delta \mathcal{S}(R)$ define monotonic functions that match CFT charges at the fixed points:

(1+1)D:
$$c(R) = R \Delta S'(R)$$
, (3+1)D: $a(R) = R^2 \Delta S''(R) - R \Delta S'(R)$.

$$R \rightarrow 0 \text{ (UV)}: c \rightarrow c_{\text{UV}}, a \rightarrow a_{\text{UV}}; \qquad R \rightarrow \infty \text{ (IR)}: c \rightarrow c_{\text{IR}}, a \rightarrow a_{\text{IR}}.$$

Motivation 5/20

Entanglement entropy in de Sitter space

Abate-Torroba, arXiv:2411.08961

Curved background (de Sitter):

- Replace Minkowski space by de Sitter space.
- Consider spherical regions in the static patch (bounded by a cosmological horizon at $R \sim H^{-1}$).
- Same ingredients: de Sitter invariance + SSA + Markov property.

The same expressions for c(R) and a(R) hold:

(1+1)D:
$$c(R) = R \Delta S'(R)$$
, (3+1)D: $a(R) = R^2 \Delta S''(R) - R \Delta S'(R)$.

In general, for ΔS we subtract:

- The contribution of the UV fixed point
- Additional UV divergent terms, related to deformations of the conformal theory (curvature, mass).

Note: In the (3+1)D case, it was shown that $a_{\rm UV} > a_{\rm IR}$ but the monotonicity of a(R) is not proven.

We focus on a free massive scalar field theory in flat background.

- The entropy can be computed explicitly (no interactions).
- Simplicity allows for numerically testing entropic c- and a-functions.

RG interpretation:

Turning on a mass μ triggers a trivial flow:

- In the deep UV the mass becomes irrelevant and we have one massless degree of freedom ($c_{\text{UV}} = a_{\text{UV}} = 1$).
- In the deep IR the massive field decouples and there are no degrees of freedom ($c_{IR} = a_{IR} = 0$).

Goal:

- Compute $S(\mu, R)$ numerically for given theory.
- Use numerical derivatives to extract c(R) in (1+1)D and a(R) in (3+1)D.
- Check that they interpolate monotonically between 1 and 0.

Setup 7/20

(3+1)D:
$$H = \frac{1}{2} \int d^3x \left[\pi^2 + (\nabla \phi)^2 + \mu^2 \phi^2 \right]$$

We expand in spherical harmonics and impose Dirichlet BC:

$$\phi(\mathbf{x}) \; = \; \sum_{\ell \mid m} \frac{\phi_{\ell m}(r)}{r} \; Y_{\ell m}(\Omega), \qquad \pi(\mathbf{x}) \; = \; \sum_{\ell \mid m} \frac{\pi_{\ell m}(r)}{r} \; Y_{\ell m}(\Omega),$$

$$H = \sum_{\ell,m} H_{\ell m}, \qquad H_{\ell m} = \frac{1}{2} \int_0^\infty dr \left[\pi_{\ell m}^2 + (\partial_r \phi_{\ell m})^2 + \left(\frac{\ell(\ell+1)}{r^2} + \mu^2 \right) \phi_{\ell m}^2 \right]$$

We discretize the radial coordinate $r_i = \epsilon i$ with $i = 1, \dots, N$:

$$\phi_{\ell m}(r) \rightarrow \frac{1}{\sqrt{\epsilon}} \phi_{\ell m,i}, \quad \pi_{\ell m}(r) \rightarrow \frac{1}{\sqrt{\epsilon}} \pi_{\ell m,i},$$

$$H_{\ell m} = \frac{1}{2} \sum_{i=1}^{N} \left(\pi_{\ell m,i}^{2} + \sum_{j=1}^{N} \phi_{\ell m,i} K_{ij}^{(\ell m)} \phi_{\ell m,j} \right)$$

Coupling matrix:

$$K_{ij}^{(\ell m)} = \frac{1}{\epsilon^2} \left[\left(2 + \mu^2 \epsilon^2 + \frac{\ell(\ell+1)}{i^2} \right) \delta_{ij} - \delta_{i,j+1} - \delta_{i+1,j} \right]$$

The wave function that describes the modes of each (ℓ, m) -sector at their ground state is a Gaussian state:

$$\Psi(\phi_{\ell m}) = \left(\det \frac{\Omega}{\pi}\right)^{1/4} e^{-\frac{1}{2}\phi_{\ell m}^T\Omega\,\phi_{\ell m}},$$

where $\Omega = K^{1/2}$ and $\phi_{\ell m}^T = [\phi_{\ell m,1}, \dots, \phi_{\ell m,N}]$.

We assume an entangling surface of radius $R = (n + \frac{1}{2}) \epsilon$:

- Subsystem *A*: oscillators 1 to *n*.
- Subsystem C: oscillators n + 1 to N (complementary).

 Setup
 9 / 20

Numerical EE: correlation functions method

The entanglement entropy of Gaussian states can be calculated by making use of correlation functions. (Sorkin 2012) For every ℓ , m:

• Define the $2N \times 2N$ matrix $\mathcal{M} = 2iJ\text{Re }(M)$, where

$$M = \begin{pmatrix} \langle \phi_i \phi_j \rangle & \langle \phi_i \pi_j \rangle \\ \langle \phi_i \pi_j \rangle^T & \langle \pi_i \pi_j \rangle \end{pmatrix}, \qquad J = \begin{pmatrix} 0 & I \\ -I & 0 \end{pmatrix}.$$

• The $2n \times 2n$ block A of this matrix for subsystem A is

$$\mathcal{M}_A = i egin{pmatrix} 0 & (\Omega)_A \ - \left(\Omega^{-1}
ight)_A & 0 \end{pmatrix}.$$

- Its eigenvalues come in pairs $\pm \lambda_i$ and satisfy $|\lambda_i| \geq 1$.
- The entanglement entropy can be computed as

$$\mathcal{S}_{\ell m} = \sum_{i=0}^{n} \left(\frac{\lambda_i + 1}{2} \log \frac{\lambda_i + 1}{2} - \frac{\lambda_i - 1}{2} \log \frac{\lambda_i - 1}{2} \right),$$

where the sum is performed only over the positive eigenvalues.

Numerical method 10 / 20

Lohmayer-Neuberger-Schwimmer-Theisen, Phys.Lett.B685:222-227,2010

(a) Finite-size effects (FSE)

- We introduce an IR cutoff $1/L = 1/(N\epsilon)$.
- We determine the finite-size effects for every ℓ up to 220.
- The FSE are captured by the expansion

$$\mathcal{S}_{\ell}(n,N,\mu) = \mathcal{S}_{\ell,\infty}(n,\mu) + \sum_{k=0}^{k_{\mathsf{max}}} rac{\mathcal{S}_{\ell}^{(k)}(n,\mu)}{N^{(2\ell+2+k)}},$$

• We subtract the FSE by keeping $S_{\ell,\infty}(n)$.

Numerical method 11/20

- (b) Limit $\ell \to \infty$
 - We study the truncated sum

$$\mathcal{S}_{\infty}(n,\mu;\ell_{\mathsf{max}}) = \sum_{\ell=0}^{\ell_{\mathsf{max}}} (2\ell+1) \mathcal{S}_{\ell,\infty}(n,\mu)$$

as a function of ℓ_{max} ($\ell_{\text{max}} \leq 10^6$).

The sum behaves as

$$\mathcal{S}_{\infty}(n,\mu;\ell_{\mathsf{max}}) = \mathcal{S}_{\infty}(n,\mu) + \sum_{i=1}^{l_{\mathsf{max}}} rac{1}{\ell_{\mathsf{max}}^{2i}} \left(a_i(n,\mu) + b_i(n,\mu) \ln \ell_{\mathsf{max}}
ight)$$

- We obtain the limit $\ell_{\max} \to \infty$ by keeping $S_{\infty}(n, \mu)$.
- (c) Dependence on $R=\left(n+\frac{1}{2}\right)\epsilon$ and μ (numerical fits)

Numerical method 12 / 20

Results agree with theoretical expressions.

$$((1+1)D \equiv \ell = 0 \text{ of } (3+1)D)$$

(3+1)D entropy

(Srednicki 1993, Solodukhin 2008, Hertzberg-Wilczek 2011)

$$S(\mu, R) = c\frac{R^2}{\epsilon^2} - \frac{1}{90} \ln \frac{R}{\epsilon} + \frac{1}{6} \mu^2 R^2 \ln(\mu \epsilon) + S_{\text{fin}}(\mu R)$$

Universal logarithmic term. Coefficient is related to the coefficient of the A-type conformal anomaly.

(1+1)D entropy

(Holzhey-Larsen-Wilczek 1994, Korepin 2004, Calabrese-Cardy 2004)

$$\mathcal{S}(\mu,R) = \frac{1}{6} \ln \frac{R}{\epsilon} + \mathcal{S}_{\mathsf{fin}}(\mu R)$$

Universal logarithmic term. Coefficient is proportional to the central charge (c = 1) of the theory.

Numerical method 13 / 20

Adjusted expressions for c- and a-functions

- The expressions that give the c- and a-functions through derivatives of S(A) eliminate the divergent terms.
- In the numerical procedure, there is no need to subtract UV terms.
- We make use of the independent variable $x = \mu R$ (only dimensionless parameter).
- We adopt a specific normalization so that $c_{\rm UV}=a_{\rm UV}=1$ and $c_{\rm IR}=a_{\rm IR}=0$, as x increases from 0 to ∞ , independently of μ .

(1+1)D (*c*-function)

$$c(x) = 6x \,\mathcal{S}'(x,\mu) = 1 + 6x \,\mathcal{S}'_{fin}(x)$$

(3+1)D (a-function)

$$a(x) = -45 \left(x^2 S''(x, \mu) - x S'(x, \mu) \right) = 1 - 45 \left(x^2 S''_{\text{fin}}(x) - x S'_{\text{fin}}(x) \right)$$

Numerical method 14 / 20

• $x = \mu R \rightarrow 0$:

Analytically we find

$$\mathcal{S}(\mu R) = \frac{1}{6} \ln \frac{R}{\epsilon} + \frac{1}{6} \mu^2 R^2 \left[\ln(\mu R) + \gamma - \frac{5}{6} \right] + \cdots$$

which implies a smooth behaviour near 0:

$$c(x) = 1 + 2x^{2} \left[\ln x + \gamma - \frac{1}{3} \right] + \cdots$$

$$\lim_{x \to 0} c(x) = 1$$

• $x = \mu R \to \infty$:

We expect (deep IR, non-critical system)

$$\mathcal{S}(\mu R) = \frac{1}{6} \ln \frac{R}{\epsilon} - \frac{1}{6} \ln(\mu R) = -\frac{1}{6} \ln(\mu \epsilon)$$

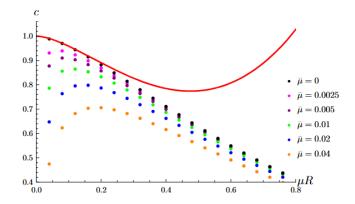
$$\lim_{x \to \infty} c(x) = 0$$

c-function

c-function: numerical technicalities

For $x \to 0$, we need $\bar{\mu} = \mu \epsilon \to 0$ to remove UV cutoff artifacts. To do that:

- We compute S(R) for several $\bar{\mu}$.
- We perform numerical fits with $\bar{\mu}$ for fixed $x = \mu R$.
- Take limit $\bar{\mu} \to 0$.



The *c*-function interpolates between 1 and 0 monotonically.

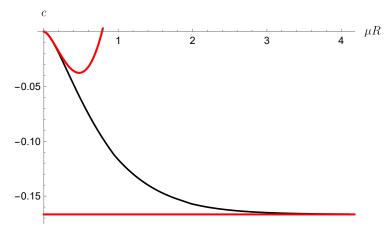
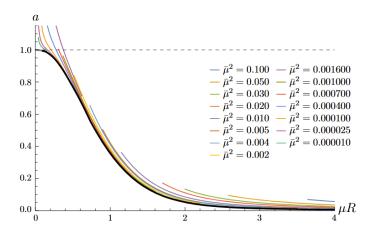


Figure: The c-function in terms of μR , along with the asymptotic expressions for small and large μR .

c-function 17/20

No analytic expressions for $x \to 0$ and $x \to \infty$. Same numerical procedure.

The a-function interpolates between 1 and 0 monotonically.



1. F-function in (2+1)D

- Replace intervals/balls ((1+1)D/(3+1)D) with disks in 2+1D OFT.
- Define an entropic F(R)-function from $S_{disk}(R)$ (related to a finite term).

2. Extention to curved backgrounds (de Sitter):

- Repeat the numerical analysis for free massive scalar in dS, using appropriate coordinates.
- Use entropic c-, F- and a-functions in dS and test monotonicity beyond flat space.

3. Interacting theories and non-trivial fixed points:

- Include interactions for non-trivial fixed points.
- Compute entropic c-, F-, and a-functions.

Prospects 19/20

Thank you!